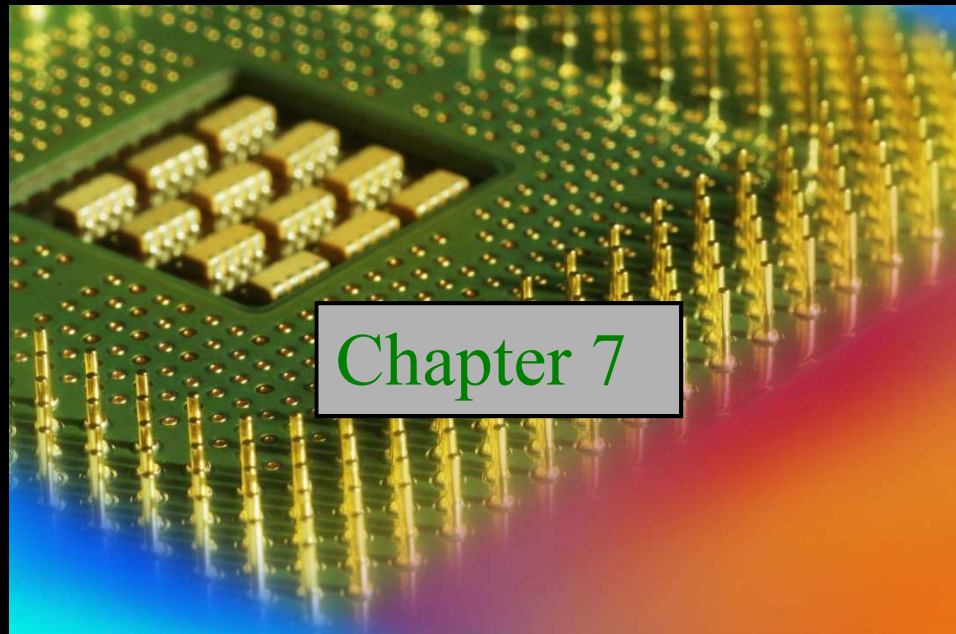


# Digital Fundamentals

Tenth Edition

Floyd



Chapter 7

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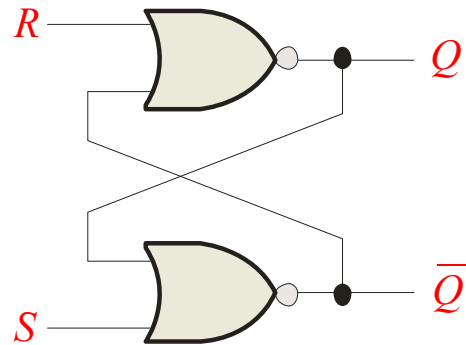
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# Summary

## Latches

A **latch** is a temporary storage device that has two stable states (bistable). It is a basic form of memory.

The S-R (Set-Reset) latch is the most basic type. It can be constructed from NOR gates or NAND gates. With NOR gates, the latch responds to active-HIGH inputs; with NAND gates, it responds to active-LOW inputs.



NOR Active-HIGH Latch

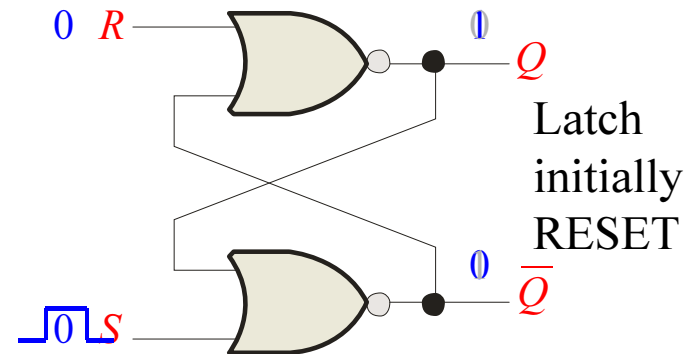
# Summary

## Latches

The active-HIGH  $S$ - $R$  latch is in a stable (latched) condition when both inputs are LOW.

Assume the latch is initially RESET ( $Q = 0$ ) and the inputs are at their inactive level (0). To SET the latch ( $Q = 1$ ), a momentary HIGH signal is applied to the  $S$  input while the  $R$  remains LOW.

To RESET the latch ( $Q = 0$ ), a momentary HIGH signal is applied to the  $R$  input while the  $S$  remains LOW.



# Summary

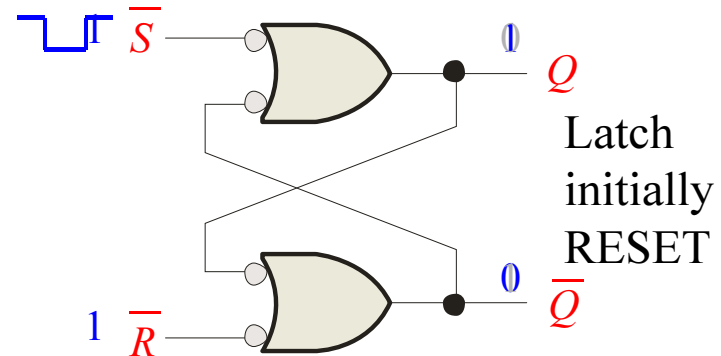
## Latches

The active-LOW  $\bar{S}$ - $\bar{R}$  latch is in a stable (latched) condition when both inputs are HIGH.

Assume the latch is initially RESET ( $Q = 0$ ) and the inputs are at their inactive level (1). To SET the latch ( $Q = 1$ ), a momentary LOW signal is applied to the  $\bar{S}$  input while the  $\bar{R}$  remains HIGH.

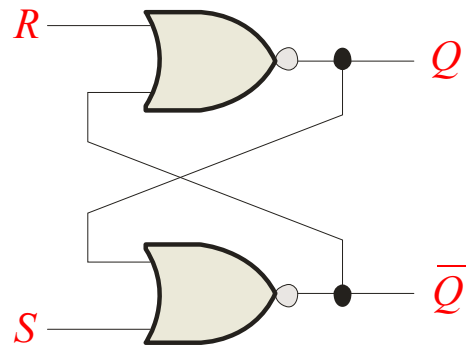
To RESET the latch a momentary LOW is applied to the  $\bar{R}$  input while  $\bar{S}$  is HIGH.

Never apply an active set and reset at the same time (invalid).

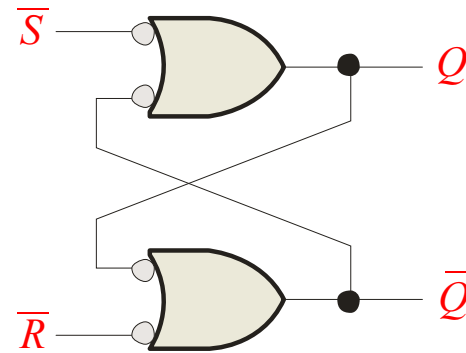


# Summary

## Latches



NOR Active-HIGH Latch



NAND Active-LOW Latch

| INPUTS    |           | OUTPUTS |           | COMMENTS                                   |
|-----------|-----------|---------|-----------|--|
| $\bar{S}$ | $\bar{R}$ | $Q$     | $\bar{Q}$ |  |
| 1         | 1         | NC      | NC        | No change. Latch remains in present state. |
| 0         | 1         | 1       | 0         | Latch SET.                                 |
| 1         | 0         | 0       | 1         | Latch RESET.                               |
| 0         | 0         | 1       | 1         | Invalid condition                          |

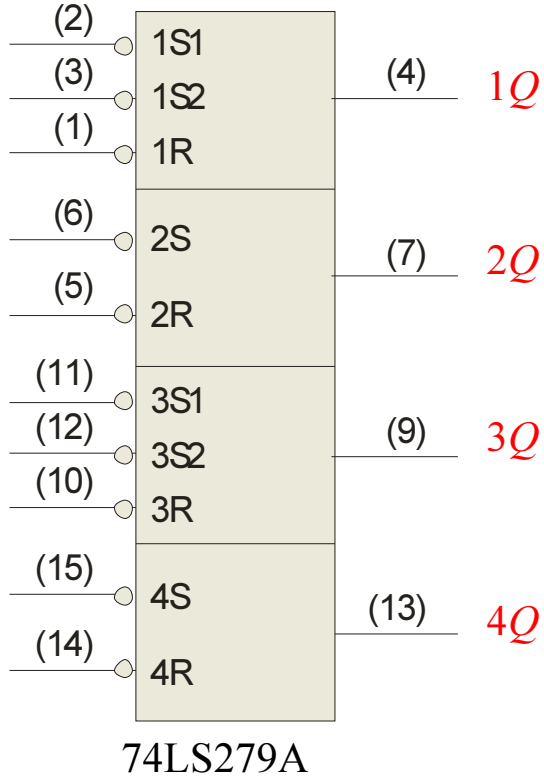
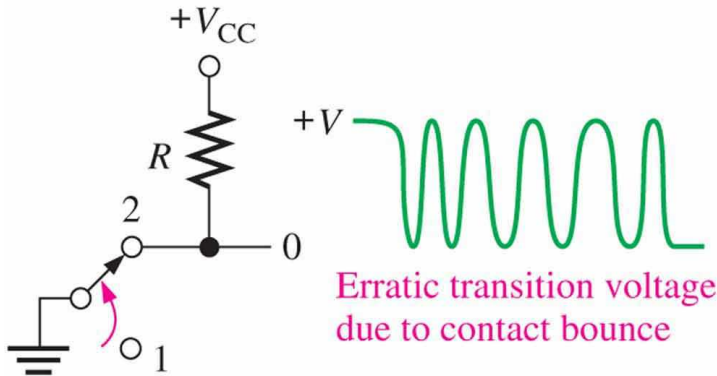
# Summary

## Latches

The active-LOW  $\bar{S}$ - $\bar{R}$  latch is available as the 74LS279A IC.

It features four internal latches with two having two  $\bar{S}$  inputs. To SET any of the latches, the  $\bar{S}$  line is pulsed low. It is available in several packages.

$\bar{S}$ - $\bar{R}$  latches are frequently used for switch debounce circuits as shown:

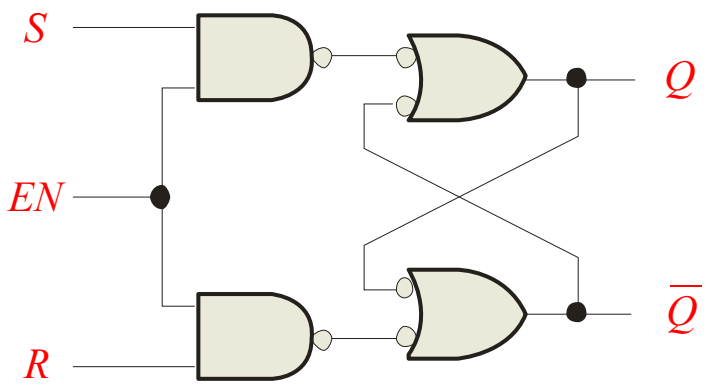


# Summary

## Gated S-R Latches

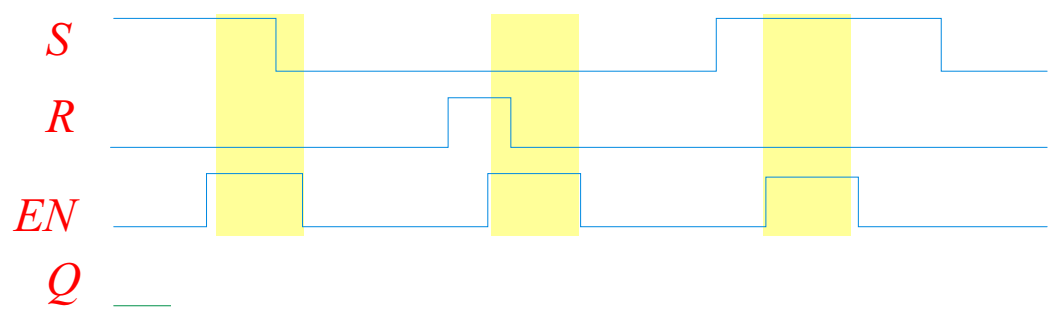
A gated latch is a variation on the basic latch.

The gated latch has an additional input, called enable ( $EN$ ) that must be HIGH in order for the latch to respond to the  $S$  and  $R$  inputs.



**Example** Show the  $Q$  output with relation to the input signals. Assume  $Q$  starts LOW.

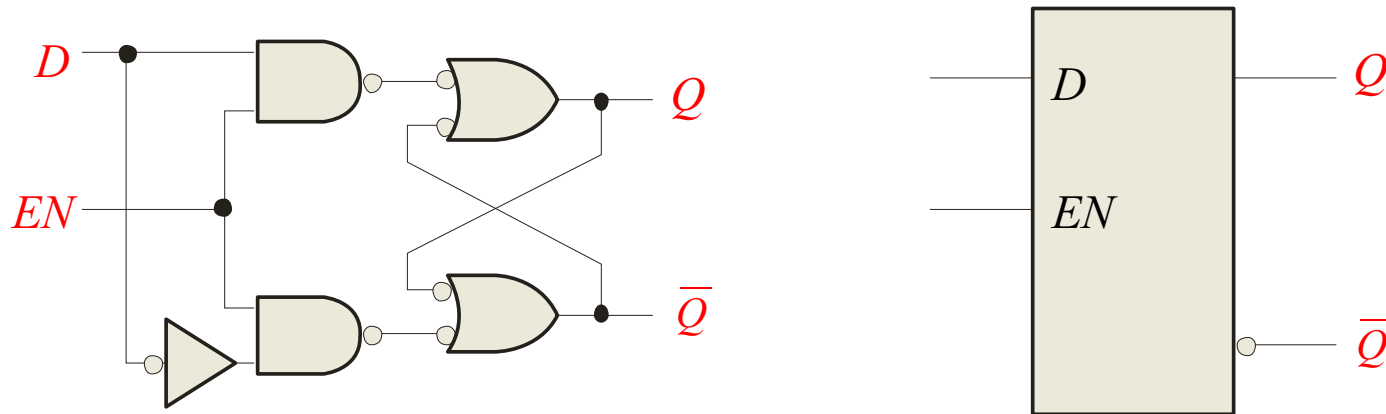
**Solution** Keep in mind that  $S$  and  $R$  are only active when  $EN$  is HIGH.



# Summary

## Gated D Latches

The  $D$  latch is an variation of the  $S$ - $R$  latch but combines the  $S$  and  $R$  inputs into a single  $D$  input as shown:



A simple rule for the  $D$  latch is:

$Q$  follows  $D$  when the Enable is active.

# Summary

## Gated D Latches

The truth table for the  $D$  latch summarizes its operation. If  $EN$  is LOW, then there is no change in the output and it is latched.

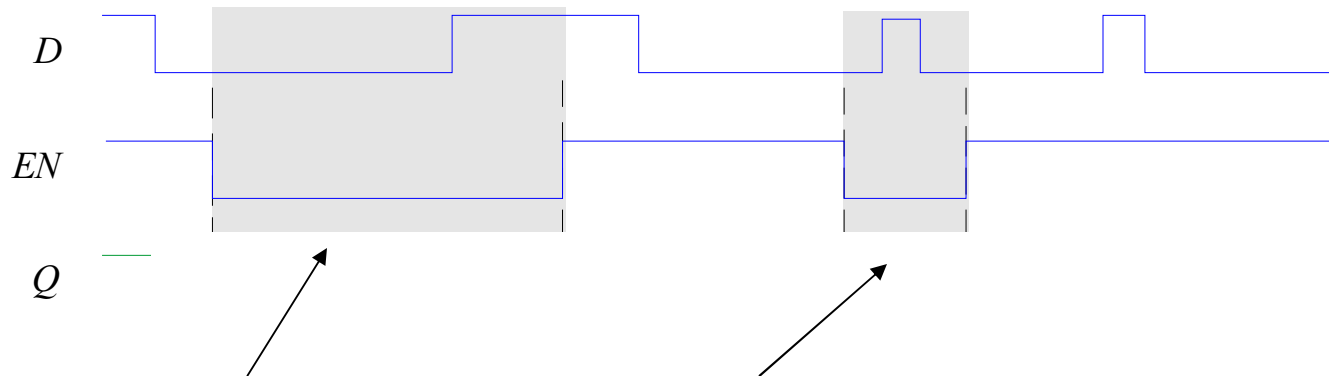
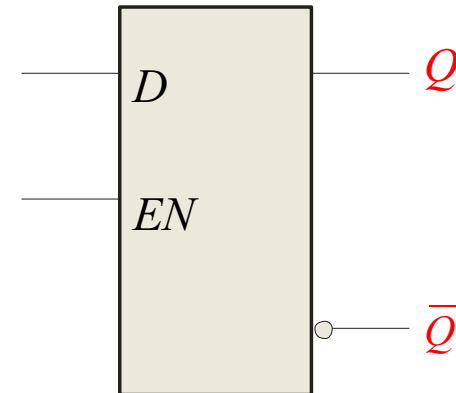
| Inputs |      | Outputs |             | Comments  |
|--------|------|---------|-------------|-----------|
| $D$    | $EN$ | $Q$     | $\bar{Q}$   |           |
| 0      | 1    | 0       | 1           | RESET     |
| 1      | 1    | 1       | 0           | SET       |
| X      | 0    | $Q_0$   | $\bar{Q}_0$ | No change |

# Summary

## Gated D Latches

### Example

Determine the  $Q$  output for the  $D$  latch, given the inputs shown.



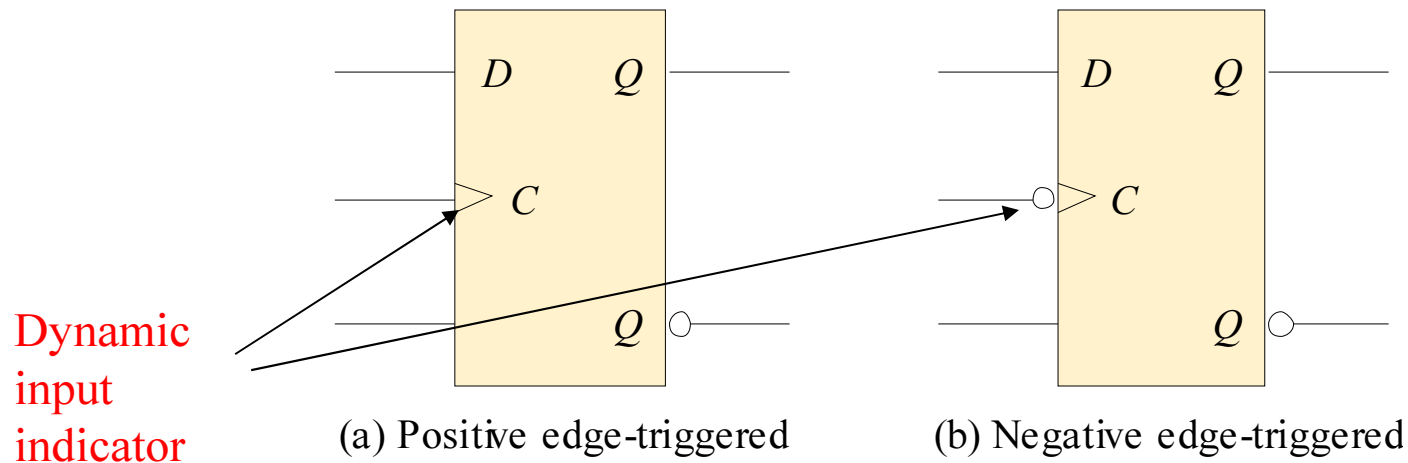
Notice that the Enable is not active during these times, so the output is latched.

# Summary

## Flip-flops

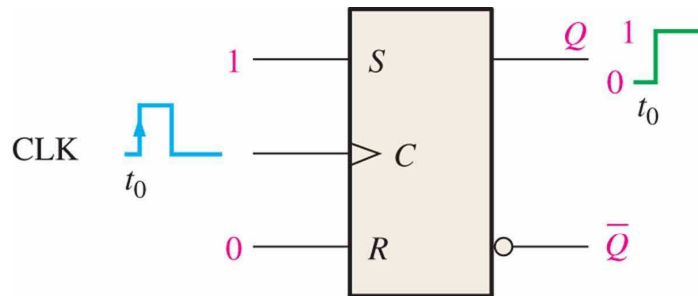
A flip-flop differs from a latch in the manner it changes states. A flip-flop is a clocked device, in which only the clock edge determines when a new bit is entered.

The active edge can be positive or negative.

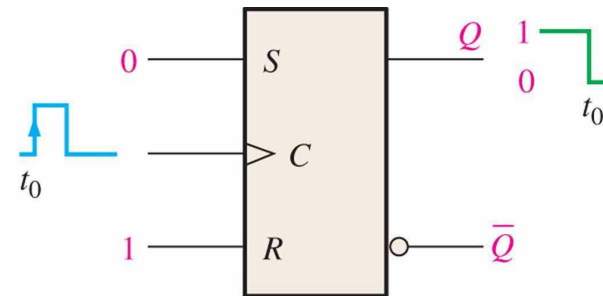


# Summary

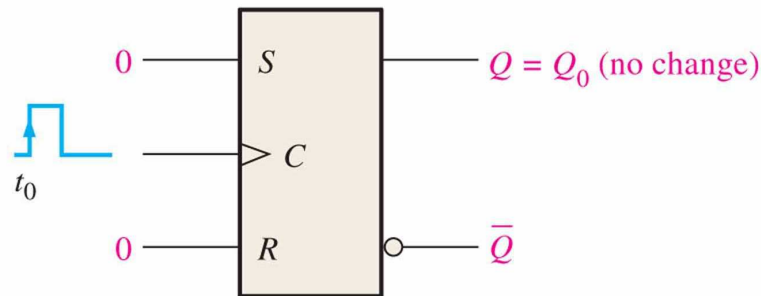
## S-R Flip-flops



(a)  $S = 1, R = 0$  flip-flop SETS on positive clock edge. (If already SET, it remains SET.)



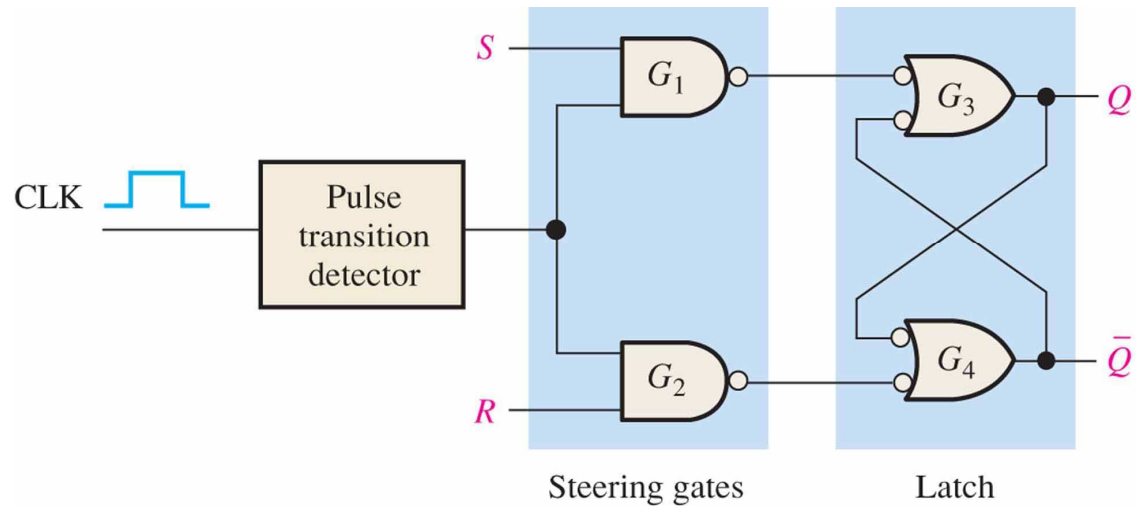
(b)  $S = 0, R = 1$  flip-flop RESETS on positive clock edge. (If already RESET, it remains RESET.)



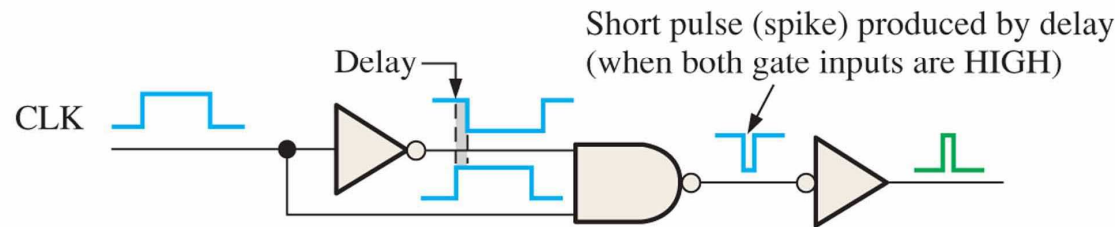
(c)  $S = 0, R = 0$  flip-flop does not change. (If SET, it remains SET; if RESET, it remains RESET.)

# Summary

## S-R Flip-flops



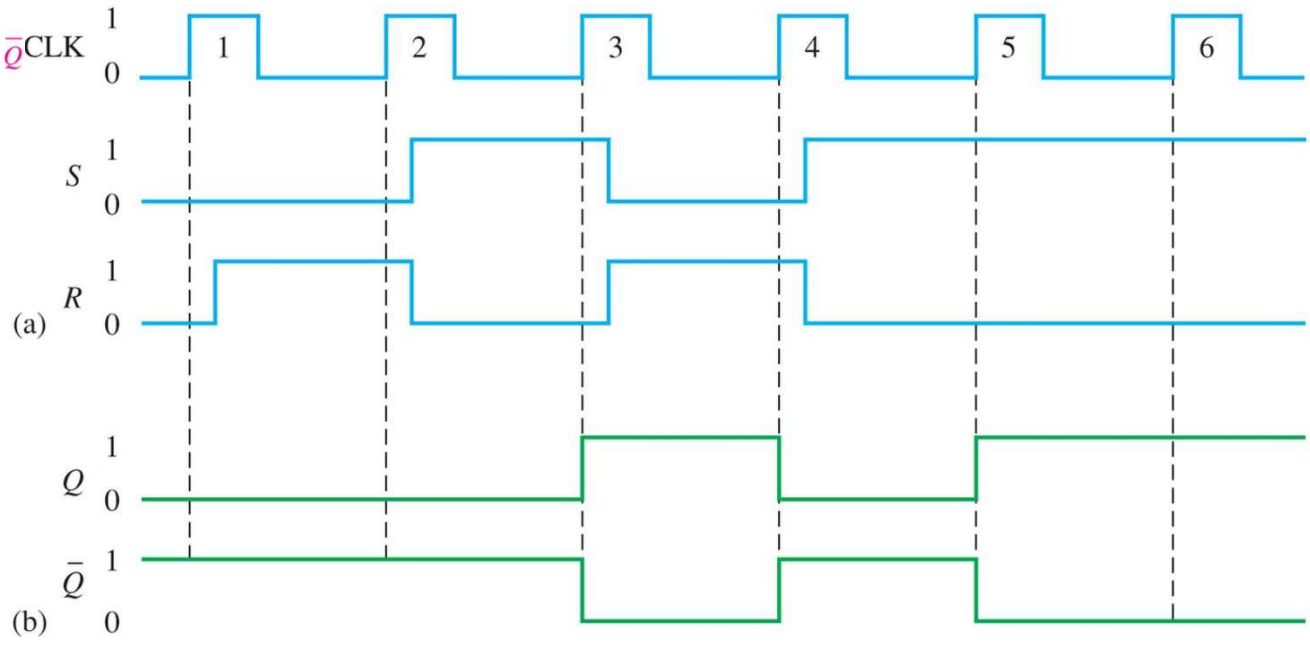
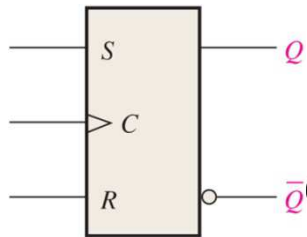
(a) A simplified logic diagram for a positive edge-triggered S-R flip-flop



(b) A type of pulse transition detector

# Summary

## S-R Flip-flops



# Summary

## D Flip-flops

The truth table for a positive-edge triggered D flip-flop shows an up arrow to remind you that it is sensitive to its *D* input only on the rising edge of the clock; otherwise it is latched. The truth table for a negative-edge triggered D flip-flop is identical except for the direction of the arrow.

| Inputs   |     | Outputs  |           | Comments |
|----------|-----|----------|-----------|----------|
| <i>D</i> | CLK | <i>Q</i> | $\bar{Q}$ |          |
| 1        | ↑   | 1        | 0         | SET      |
| 0        | ↑   | 0        | 1         | RESET    |

(a) Positive-edge triggered

| Inputs   |     | Outputs  |           | Comments |
|----------|-----|----------|-----------|----------|
| <i>D</i> | CLK | <i>Q</i> | $\bar{Q}$ |          |
| 1        | ↓   | 1        | 0         | SET      |
| 0        | ↓   | 0        | 1         | RESET    |

(b) Negative-edge triggered

# Summary

## J-K Flip-flops

The J-K flip-flop is more versatile than the D flip flop. In addition to the clock input, it has two inputs, labeled  $J$  and  $K$ . When both  $J$  and  $K = 1$ , the output changes states (toggles) on the active clock edge (in this case, the rising edge).

| Inputs |     |     | Outputs     |             | Comments  |
|--------|-----|-----|-------------|-------------|-----------|
| $J$    | $K$ | CLK | $Q$         | $\bar{Q}$   |           |
| 0      | 0   | ↑   | $Q_0$       | $\bar{Q}_0$ | No change |
| 0      | 1   | ↑   | 0           | 1           | RESET     |
| 1      | 0   | ↑   | 1           | 0           | SET       |
| 1      | 1   | ↑   | $\bar{Q}_0$ | $Q_0$       | Toggle    |

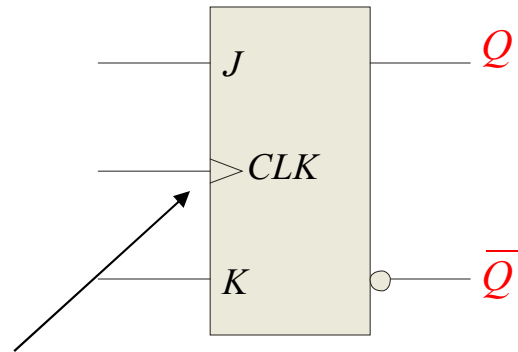
# Summary

## J-K Flip-flops

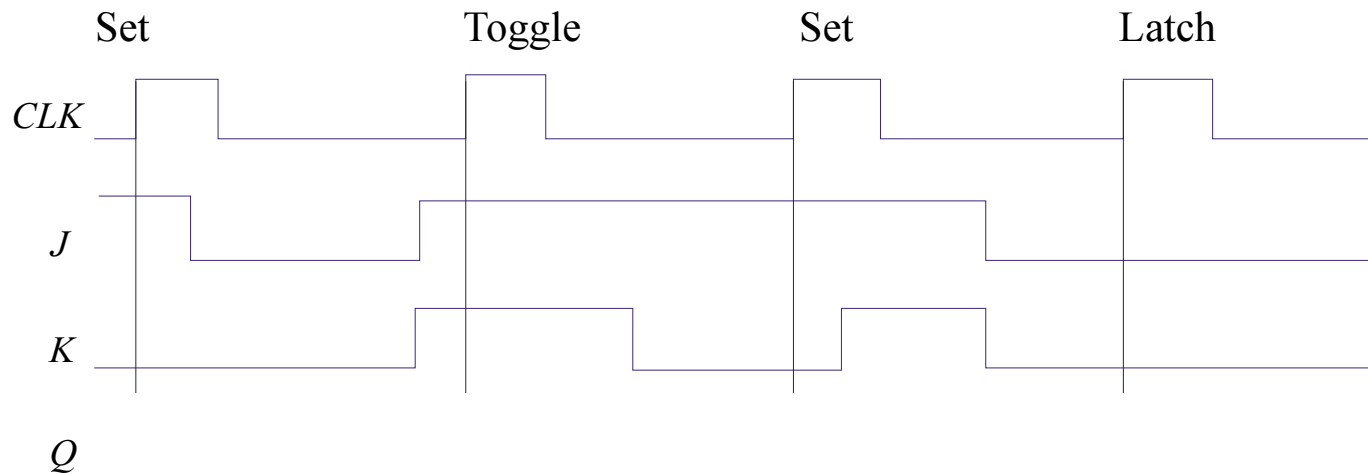
### Example

Determine the  $Q$  output for the  $J$ - $K$  flip-flop, given the inputs shown.

Notice that the outputs change on the leading edge of the clock.



### Solution

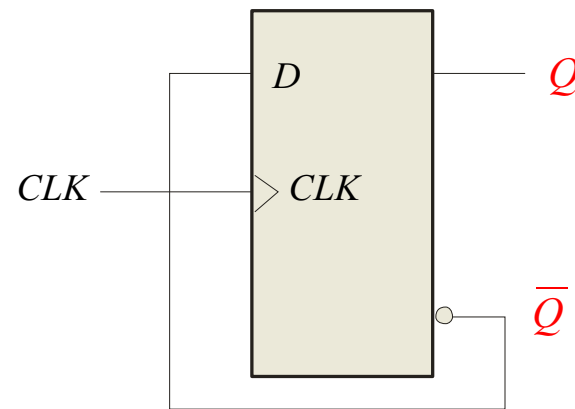


# Summary

## Flip-flops

A D-flip-flop does not have a toggle mode like the J-K flip-flop, but you can hardwire a toggle mode by connecting  $\bar{Q}$  back to  $D$  as shown. This is useful in some counters as you will see in Chapter 8.

For example, if  $Q$  is LOW,  $\bar{Q}$  is HIGH and the flip-flop will toggle on the next clock edge. Because the flip-flop only changes on the active edge, the output will only change once for each clock pulse.



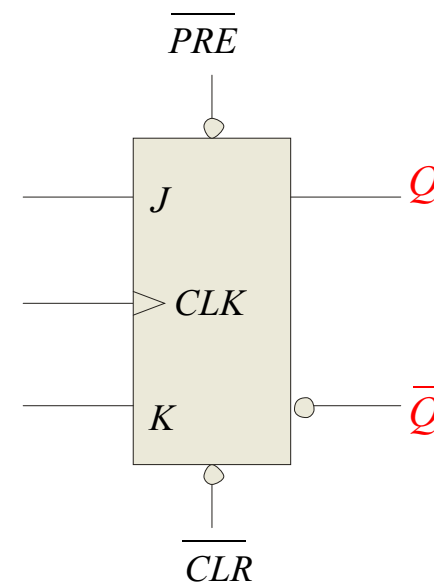
D flip-flop hardwired for a toggle mode

# Summary

## Asynchronous Preset and Clear

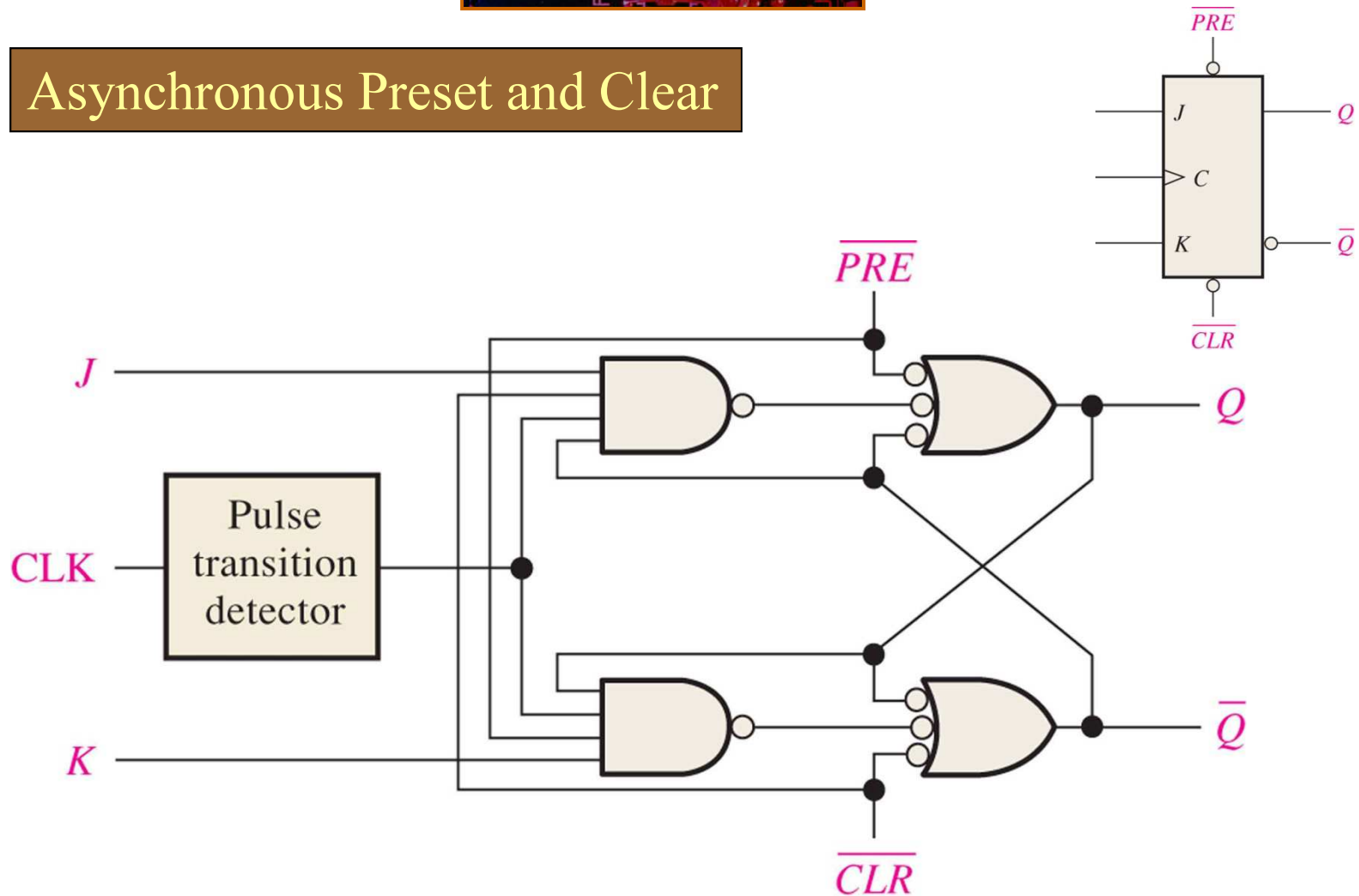
Synchronous inputs are transferred in the triggering edge of the clock (for example the  $D$  or  $J$ - $K$  inputs). Most flip-flops have other inputs that are *asynchronous*, meaning they affect the output independent of the clock.

Two such inputs are normally labeled preset ( $PRE$ ) and clear ( $CLR$ ). These inputs are usually active LOW. A J-K flip flop with active LOW preset and CLR is shown.



# Summary

## Asynchronous Preset and Clear



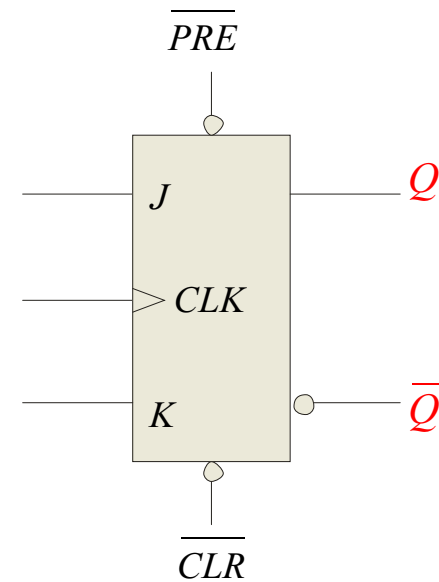
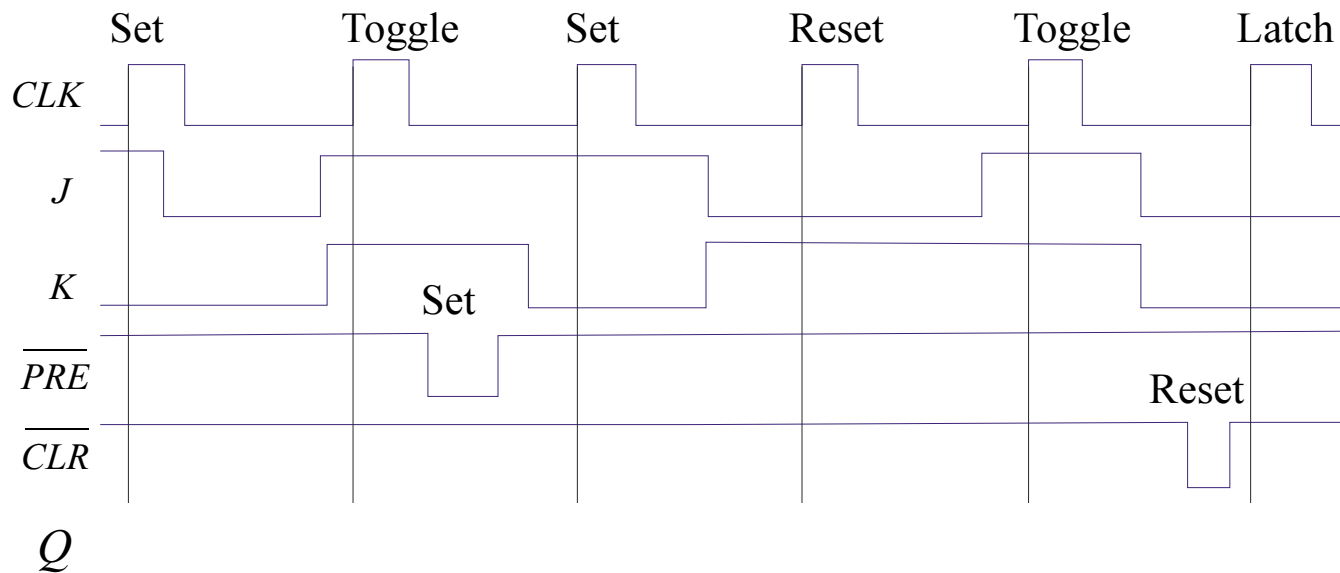
# Summary

## Flip-flops

### Example

Determine the  $Q$  output for the  $J$ - $K$  flip-flop, given the inputs shown.

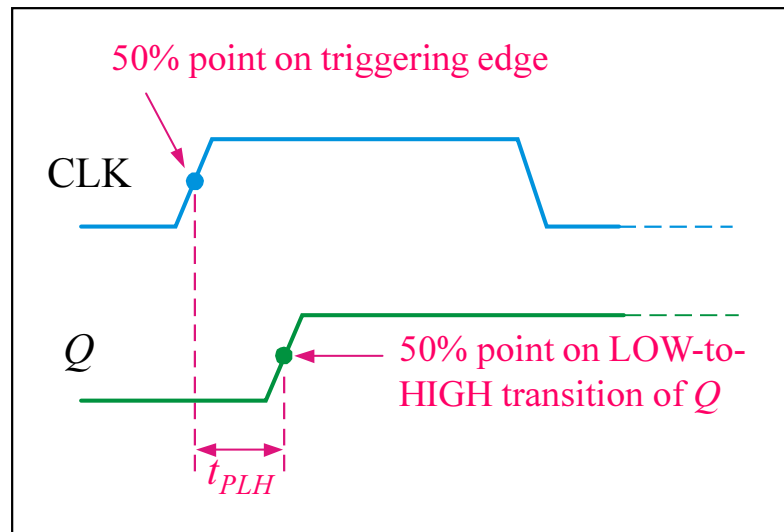
### Solution



# Summary

## Flip-flop Characteristics

**Propagation delay time** is specified for the rising and falling outputs. It is measured between the 50% level of the clock to the 50% level of the output transition.

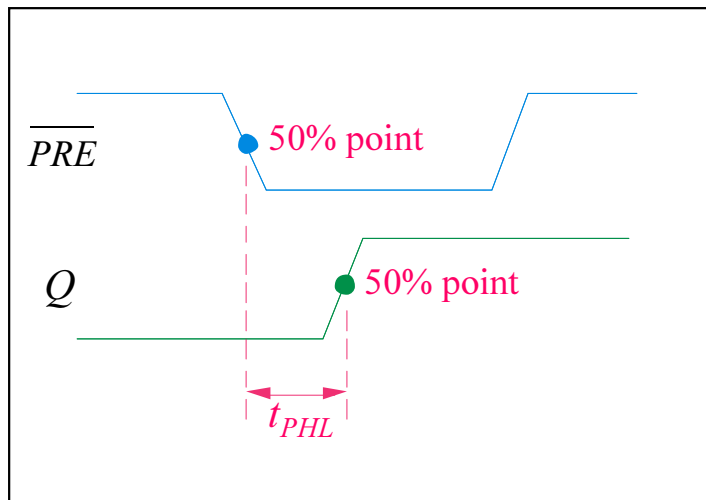


The typical propagation delay time for the 74AHC family (CMOS) is 4 ns. Even faster logic is available for specialized applications.

# Summary

## Flip-flop Characteristics

Another **propagation delay time** specification is the time required for an *asynchronous* input to cause a change in the output. Again it is measured from the 50% levels. The 74AHC family has specified delay times under 5 ns.

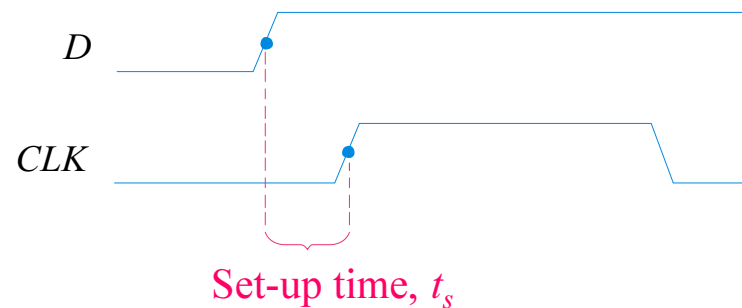


# Summary

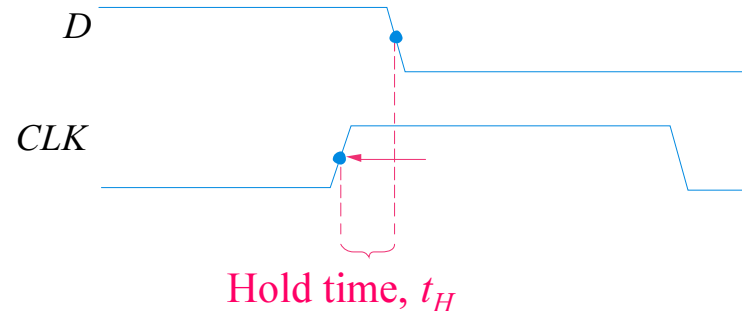
## Flip-flop Characteristics

**Set-up time** and **hold time** are times required before and after the clock transition that data must be present to be reliably clocked into the flip-flop.

**Setup time** is the minimum time for the data to be present *before* the clock.



**Hold time** is the minimum time for the data to *remain* after the clock.



# Summary

## Flip-flop Characteristics

Other specifications include maximum clock frequency, minimum pulse widths for various inputs, and power dissipation. The power dissipation is the product of the supply voltage and the average current required.

A useful comparison between logic families is the **speed-power product** which uses two of the specifications discussed: the average propagation delay and the average power dissipation. The unit is energy.

**Example** What is the speed-power product for 74AHC74A? Use the data from Table 7-5 to determine the answer.

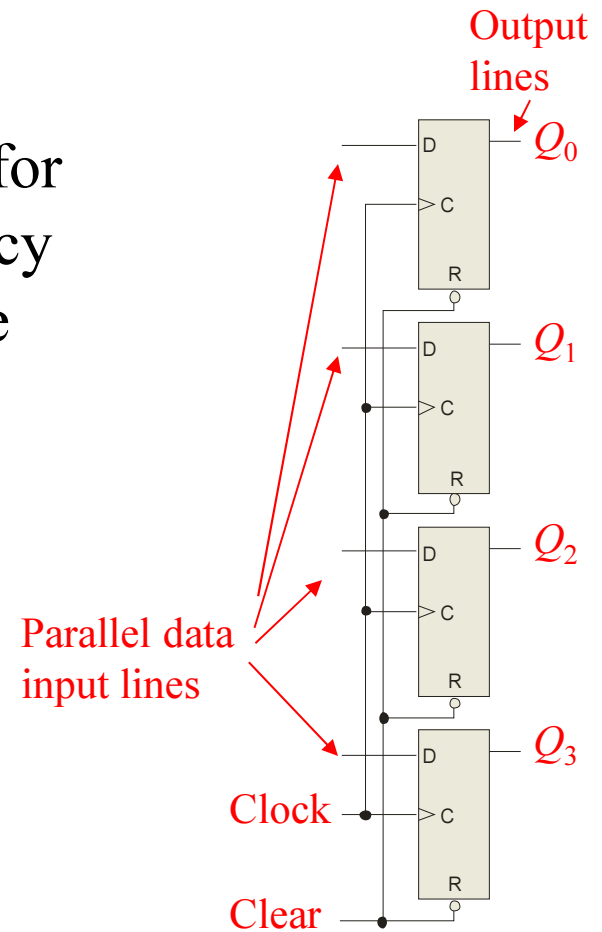
**Solution** From Table 7-5, the average propagation delay is 4.6 ns. The quiescent power dissipated is 1.1 mW. Therefore, the speed-power product is **5 pJ**

# Summary

## Flip-flop Applications

Principal flip-flop applications are for temporary data storage, as frequency dividers, and in counters (which are covered in detail in Chapter 8).

Typically, for **data storage** applications, a group of flip-flops are connected to parallel data lines and clocked together. Data is stored until the next clock pulse.



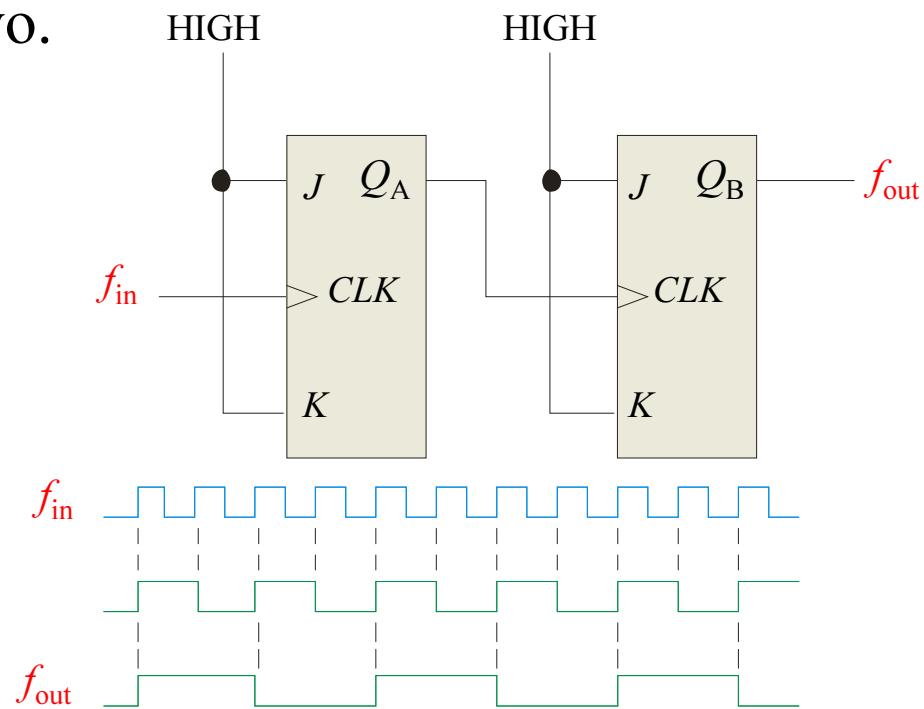
# Summary

## Flip-flop Applications

For **frequency division**, it is simple to use a flip-flop in the toggle mode or to chain a series of toggle flip flops to continue to divide by two.

One flip-flop will divide  $f_{in}$  by 2, two flip-flops will divide  $f_{in}$  by 4 (and so on). A side benefit of frequency division is that the output has an exact 50% duty cycle.

Waveforms:



# Homework 10

- Chapter 7 (5, 8, 16, 17, 25)